

basic education

Department: Basic Education **REPUBLIC OF SOUTH AFRICA**

NATIONAL SENIOR CERTIFICATE

GRADE 12

ELECTRICAL TECHNOLOGY

EXEMPLAR 2014

MEMORANDUM

MARKS: 200

I.

This memorandum consists of 13 pages.

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INSTRUCTIONS TO THE MARKERS

- 1. All questions with multiple answers imply that any relevant, acceptable answer should be considered.
- 2. Calculations:
 - 2.1 All calculations must show the formulae.
 - 2.2 Substitution of values must be done correctly.
 - 2.3 All answers MUST contain the correct unit to be considered.
 - 2.4 Alternative methods must be considered, provided that the same answer is obtained.
 - 2.5 Where an incorrect answer could be carried over to the next step, the first answer will be deemed incorrect. However, should the incorrect answer be carried over correctly, the marker has to recalculate the values, using the incorrect answer from the first calculation. If correctly used, the candidate should receive the full marks for subsequent calculations.
- 3. This memorandum is only a guide with model answers. Alternative interpretations must be considered and marked on merit. However, this principle should be applied consistently throughout the marking session at ALL marking centres.

QUESTION 1: OCCUPATIONAL HEALTH AND SAFETY

1.1	Working on a live system with exposed conductors. \checkmark Working with portable electric equipment that is not insulated correctly.			
	Using electrical machines without using the required safety equipment or clothing.	(1)		

- 1.2Poor ventilation. ✓
Poor lighting(1)
- 1.3 First aid must be immediately given to any injured people. ✓
 The situation must be immediately assessed and the person designated to deal with medical emergencies must be informed. (1)
- 1.4 If a workshop has no wheel-chair access, this will make it difficult ✓ for people with physical disabilities to work in that workshop. This is an infringement of their right to ease of access. ✓
- 1.5 No person may enter or remain in a workplace under the influence of drugs as he may place himself and other persons ✓ in danger while operating machinery. ✓ It is unethical because it is an infringement of the right to work in a safe environment.
- 1.6 Risk analysis is a process that will inform workers ✓in the workshop about good housekeeping ✓ and safety practices ✓ improving the safety of all workers and equipment in the workshop.

QUESTION 2: THREE-PHASE AC GENERATION

- 2.1 To measure the amount of power \checkmark consumed by a consumer over a period of time \checkmark (2)
- 2.2 For alternators of similar frame sizes, three-phase machines deliver a higher power than single-phase machines. ✓
 It is more versatile since, when connected in star, it can deliver both line and phase voltage. ✓
 Three-phase systems are easier to connect in parallel than single-phase systems.

(2)

(2)

(2)

(3) **[10]**

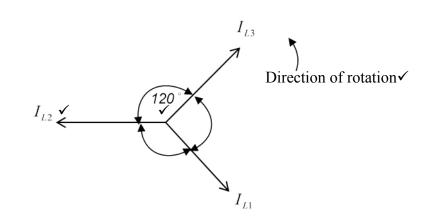
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2.3

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(3)

(3)



One mark for correct rotation direction One mark for correct labelling of the phasor One mark for mutual phase difference of 120°

2.4 2.4.1
$$P = W_1 + W_2 \checkmark$$

= $(4 + 17,5) \checkmark$
= $21,5 \, kW \checkmark$ (3)

2.4.2
$$P = \sqrt{3}V_{L}I_{L}Cos\theta$$

$$I_{L} = \frac{P}{\sqrt{3} \times V_{L} \times Cos\theta} \quad \checkmark \text{ (One mark for the formula)}$$

$$I_{L} = \frac{21500}{\sqrt{3} \times 380 \times 0.8} \quad \checkmark$$

$$I_{L} = 40.83A \quad \checkmark$$
(3)

2.5

2.5.1

$$S = \sqrt{3} x V_L I_L$$
$$V_L = \frac{S}{\sqrt{3}xI_l} \checkmark$$
$$V_L = \frac{20 x 1000}{\sqrt{3} x 25} \checkmark$$
$$= 461.9 V \checkmark$$

2.5.2 $V_{L} = \sqrt{3} \times V_{ph}$ $V_{L} = \sqrt{3} \times V_{ph} \checkmark$ $V_{L} = \sqrt{3} \times V_{ph} \checkmark$ $V_{ph} = \frac{V_{L}}{\sqrt{3}} \checkmark \qquad \mathbf{OR}$ $461.9 = \sqrt{3} \times V_{ph}$ $V_{ph} = \frac{461.9}{\sqrt{3}} \checkmark$ $V_{ph} = \frac{461.9}{\sqrt{3}} \checkmark$ $V_{ph} = \frac{266,7 \, V \checkmark}{\sqrt{3}} \qquad (3)$

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2.6	Make us Make us	ower factor correcting capacitor in parallel with the load. ✓ e of synchronous motors. e of an AVR (Automatic Voltage Regulator) to assist in correcting the er Factor).	(1) [20]
QUESTI	ON 3: TH	IREE-PHASE TRANSFORMERS	20
3.1	Mutual induction ✓ Electromagnetic induction between two coils.		
3.2	Constant overloading✓ Loose connections✓ Insufficient ventilation✓ Moisture in the oil		
3.3	Buchholtz relay√		
3.4	The breather allows the movement of air into and out of the reservoir tank. \checkmark		
3.5	3.5.1	The resistance \checkmark offered to the current \checkmark flow in the windings.	(2)
	3.5.2	The quality of the iron which affects the hysteresis \checkmark of the iron and eddy current \checkmark flow in the iron.	(2)

3.6 Calculate:

3.6.1
$$V_{L(s)} = \sqrt{3}V_{ph}$$
$$V_{ph(s)} = \frac{V_{L(s)}}{\sqrt{3}} \checkmark$$
$$= \frac{380}{\sqrt{3}} \checkmark$$
$$= 219,39 V \checkmark$$
3.6.2
$$P = S \cos \theta \checkmark$$

$$P = 200\,000 \, x\,0.85 \,\checkmark$$

$$P = 170 \, kW$$
(3)

(3)

 $3.6.3 \qquad S = \sqrt{3} V_L I_L$

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$$I_L = \frac{S}{\sqrt{3}V_L} \checkmark$$

$$= \frac{200000}{\sqrt{3} \times 11000} \checkmark$$

$$= 10.5.4 \checkmark$$
(3)
[20]

QUESTION 4: THREE-PHASE MOTORS AND STARTERS

4.1 End plates ✓
Stator ✓
Rotor ✓
(3)

4.2 It can only be used for relatively small induction motors whose starting currents do not require limitation. \checkmark
Very high starting current (typically 6 to 8 times the full load current of the motor).
Thermal stress on the motor, thereby reducing its life.
Unnecessary high starting torque, even when not required by the load, thereby increased mechanical stress on the mechanical systems such as rotor shaft, bearings, gearbox, coupling, chain drive, connected equipment, etc. leading to premature failure and plant down times.

4.3 The number of poles ✓
The frequency of the supply ✓
(2)

4.4 Does the rotor turn freely or does something cause friction? ✓
Are the bearings squeaky or do they feel rough when the shaft is turned by hand? ✓
Is the motor mounted securely and are the bolts tightened properly? ✓
Is the cooling fan intact or do some of the fins appear chipped?
Are the bearings fastened properly?
Does the frame have any cracks?

4.5 To start the motor safely
4.6 4.6.1 1 - Overload unit <
2 · NC stop ✓
3 · NO start
(5)

4.6.2 The function of the overload is to protect the motor under fault conditions ✓ that result in the motor drawing in excess of the rated

current ✓ leading to possible damage of the motor. ✓

(3)

6

4.7

4.6.3 The motor is started in the star mode which reduces \checkmark the voltage across each phase \checkmark of the motor as in star V_{PH} = $\sqrt{3}$ V_L. \checkmark As the voltage across each phase is reduced, the current in each phase will also be reduced. \checkmark

(4)

- 4.6.4 The N/O start will be depressed. \checkmark This will energise the contactor C_M and C_T . The N/O_M will now close keeping both C_M and C_T energised. \checkmark The N/C_T will remain closed as the timer is timing through. \checkmark The N/C_{Λ} will still be closed as the delta contactor is not yet energised. ✓ This results in a complete circuit to the star coil energising the coil. \checkmark This results in the motor starting in star. \checkmark The timer will now time through opening the N/C_T contacts removing power from the star coil. \checkmark The N/O_T will close after the timer has timed through and with the N/C_Y now closing because the star contactor is now de-energised. \checkmark The delta path will be complete energising the delta contactor switching the motor into the delta mode. When the motor is connected across an alternating supply, alternating
- When the motor is connected across an alternating supply, alternating currents will flow in the stator windings. ✓
 - The alternating currents will set up a rotating magnetic field in and around the stator windings. ✓
 - This rotating magnetic field will sweep across the rotor conductors of the squirrel cage rotor. ✓
 - As the magnetic field sweeps over the rotor conductors the magnetic lines of flux cut the rotor conductors. ✓
 - This induces an EMF across the rotor conductors due to Lenz's law. \checkmark
 - This sets up currents in the rotor conducts which creates a rotating magnetic field in and around the rotor. ✓
 - The two magnetic fields interact causing a force to be exerted between them resulting in the rotor to rotating. ✓

(7) **[40]**

(10)

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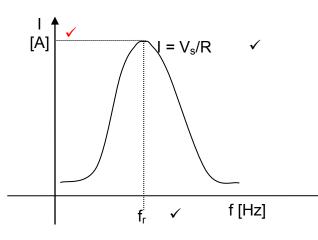
QUESTION 5: RLC

5.1 Impedance is the total opposition offered to the flow of current \checkmark by the resultant of the reactance and the resistance \checkmark of a circuit when the circuit is connected across an alternating voltage supply. \checkmark

(3)

- 5.2 When the frequency is increased, the inductive reactance will increase ✓ thus increasing the impedance ✓ of the circuit and reducing the current flowing through the circuit and hence the brightness of the lamp. ✓ (3)
- 5.3 The Q-factor is the voltage magnification \checkmark that occurs in a series RLC when the circuit is at resonant frequency. \checkmark (2)



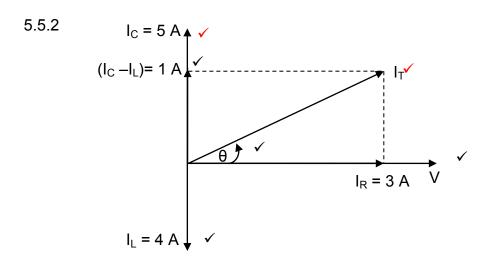


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5.5 5.5.1

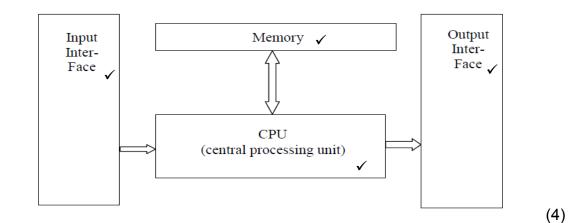
$$I_{T} = \sqrt{I_{R}^{2} + (I_{C} - I_{L})^{2}} \checkmark$$

= $\sqrt{3^{2} + (5 - 4)^{2}} \checkmark$
= 3,16 A \lambda (3)



QUESTION 6: LOGIC

- 6.1 6.1.1 Programmable Logic Controller√
 - 6.1.2



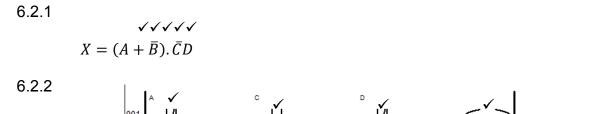
6.1.3	It improved on hard-wired relay based systems. \checkmark		(1)
6.1.4	Economical ✓ Simplified design Quick delivery Compact and standardised Improved reliability Reduced maintenance	(Any THREE)	(3)
6.1.5	Relays or contactors✓ or Thyristor control (solid state) Any low current device		(1)
6.1.6	Ladder logic✓ Instruction list ✓and Logic block diagram/Functional blocks		(3)

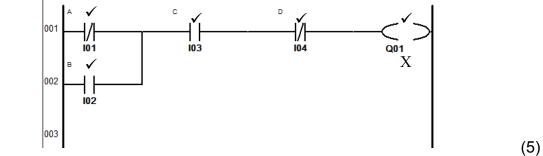
(1)

(6) **[20]** 6.2

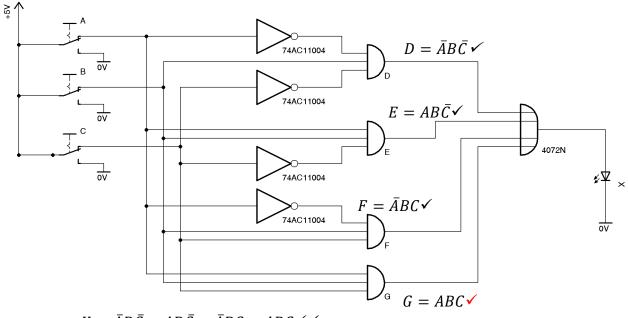
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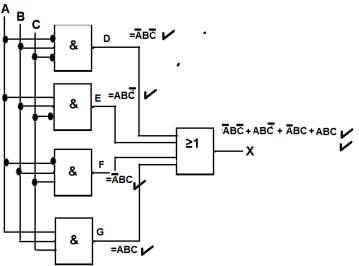






 $X = \bar{A}B\bar{C} + AB\bar{C} + \bar{A}BC + ABC\checkmark\checkmark$



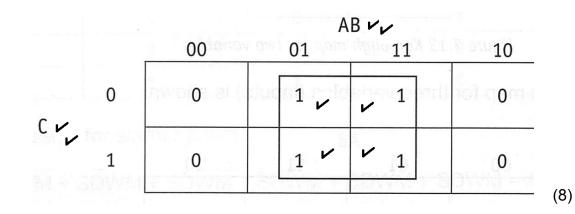


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6.5 A timer function is used to set and control ✓ the PLC program according to daily, weekly or yearly pre-set timing. ✓ The PLC will execute a task based on timing like switching the outside lights on automatically at dusk. ✓

QUESTION 7: AMPLIFIERS

- 7.1 Open-loop voltage gain A_V = infinite \checkmark Input impedance Z_{in} . = infinite \checkmark Output impedance Z_0 = zero Bandwidth = infinite Unconditional stability Differential inputs, i.e. two inputs Infinite common-mode rejection
- 7.2 The dual DC supply supplies energy to the op amp to amplify an input signal. ✓ It allows the op amp to operate with a positive and negative supply (+Vcc and –Vcc). ✓
- 7.3 Feedback is obtained when the output signal ✓of an amplifier circuit is fed back to the input of the circuit. ✓ Negative feedback is achieved when the signal is fed back to the input, out of phase with the input signal✓, thus reducing the gain of the circuit. In effect the feedback signal is subtracted from the input signal.
- 7.4 The bandwidth is increased. ✓
 The level of noise (hiss) is decreased. ✓
 The gain is decreased.
 The deformation of the input signal is reduced. (2)
- 7.5 The bandwidth is the range of frequencies \checkmark an amplifier can amplify without distorting \checkmark the output signal or losing gain. (2)

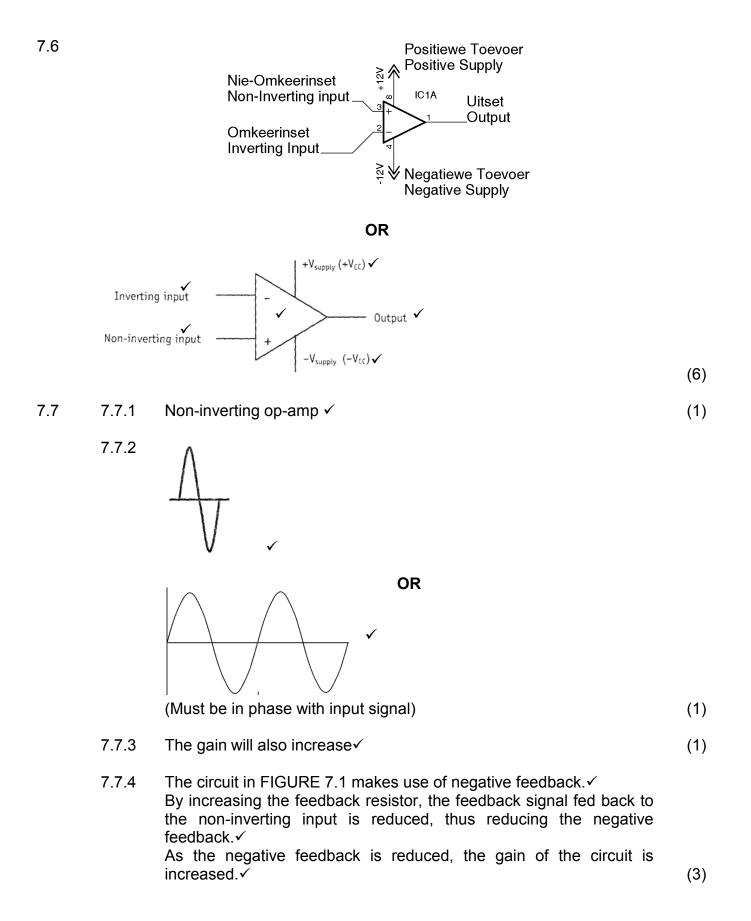
(4)

(3)

(3) **[40]**

(Any TWO) (2)

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7.8 7.8.1

$$A_V = -\frac{R_f}{R_{in}} \checkmark$$
$$= -\frac{10}{5} \checkmark$$
$$= -2 \checkmark$$

7.8.2

$$A_{V} = -\frac{V_{outf}}{V_{in}} \qquad \checkmark$$
$$\Box \quad V_{out} = -A_{V}V_{in}$$
$$= -2 x 1 \qquad \checkmark$$
$$= -2 V \qquad \checkmark$$

 \checkmark

7.9

7.9.1 Summing amplifier√

7.9.2 The inverting amplifier is often used as a mixer in audio circuits \checkmark when more than one signal is applied to the input simultaneously. \checkmark The output then becomes the sum of these input signals, from a microphone, an electric guitar or a keyboard. \checkmark

7.9.3
$$V_{out} = -(V_1 + V_2 + V_3) \checkmark$$

= $-(2 + -1 + 3) \checkmark$
= $-4V \checkmark$

7.10 7.10.1 R_1 and R_2 provide positive feedback to the non-inverting terminal \checkmark causing the output to remain at its state \checkmark until the inverting terminal receives a pulse to change the state of the output \checkmark and they again provide feedback to remain in its state.

- 7.10.2 The input capacitors firstly act as decouplers to decouple the DC from the input stage to the amplifier, \checkmark only passing changes in input voltage. ✓ Incoming wave signals are therefore converted into short pulses. \checkmark The capacitors are then used to trigger the op amp to change between its two saturation states. \checkmark
- 7.10.3 It has two stable states, \checkmark one positive \checkmark and one negative \checkmark saturation states i.e. High and Low/Set and Reset.

(3) [50]

(4)

(3)

(3)

(1)

(3)

(3)

(3)